

# Introduction

## Why Monitor Machine Condition?

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### ■ In any plant we have assets (big or small) that we want to:

- Protect from damage
- Prevent problems that would result in a loss of production
- Assure or improve Quality
- Reduce maintenance costs



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# Protect from Damage

## Monitor the Overall (total) Vibration

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Most Protection Monitors measure the Overall level.

### Mitigate Damage to...

- Protect Investments
- Protect Personnel
- Protect Environment

Danger Severe vibration, damage and/or failure possible

**Danger**

### Investigate Condition

- Plan Maintenance

Alert Moderate vibration. Cause should be investigated.

**Alert**

Overall

Normal

Machine is balanced but faults may be present.

Operation at a level above "Danger" may result in significant damage, and possibly catastrophic failure. Maintenance performed before this point will be less expensive and require less time to perform.

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# Monitoring Machine Condition...

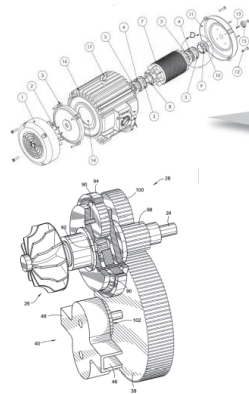
Requires detecting and identifying faults

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- Overall vibration does not provide insight into what is **causing** the vibration
- To understand **what is causing** the vibration, monitor the **Indicators of fault...**

## Mechanical attributes

- Speed
- Type of bearings
- Number of impeller vanes
- Number of fan blades
- Number of gear teeth
- etc.



## Electrical attributes

- Speed
- Type of motor
- Line frequency
- Number of rotor bars
- Number of stator slots
- etc.

Identifying fault indicators requires knowing basic characteristics of the machine.

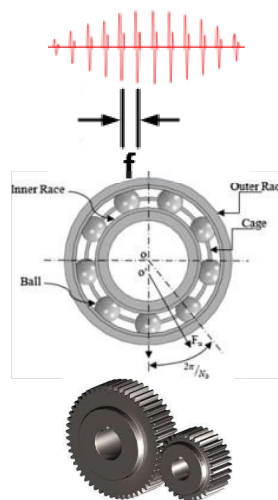
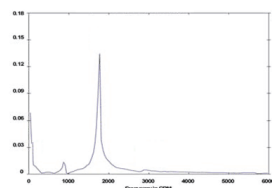
# Monitoring Machine Condition...

Faults are identified by the **frequency** of the vibration it causes

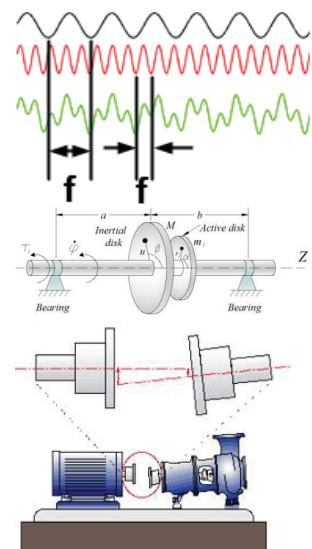
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- Faults induce **repetitive** impact or cyclic forces at specific, predictable frequencies (**f**).

Except for structural resonances which simply "ring" at the resonant frequency when excited.



Pits or scratches on balls, broken or damaged gear teeth...

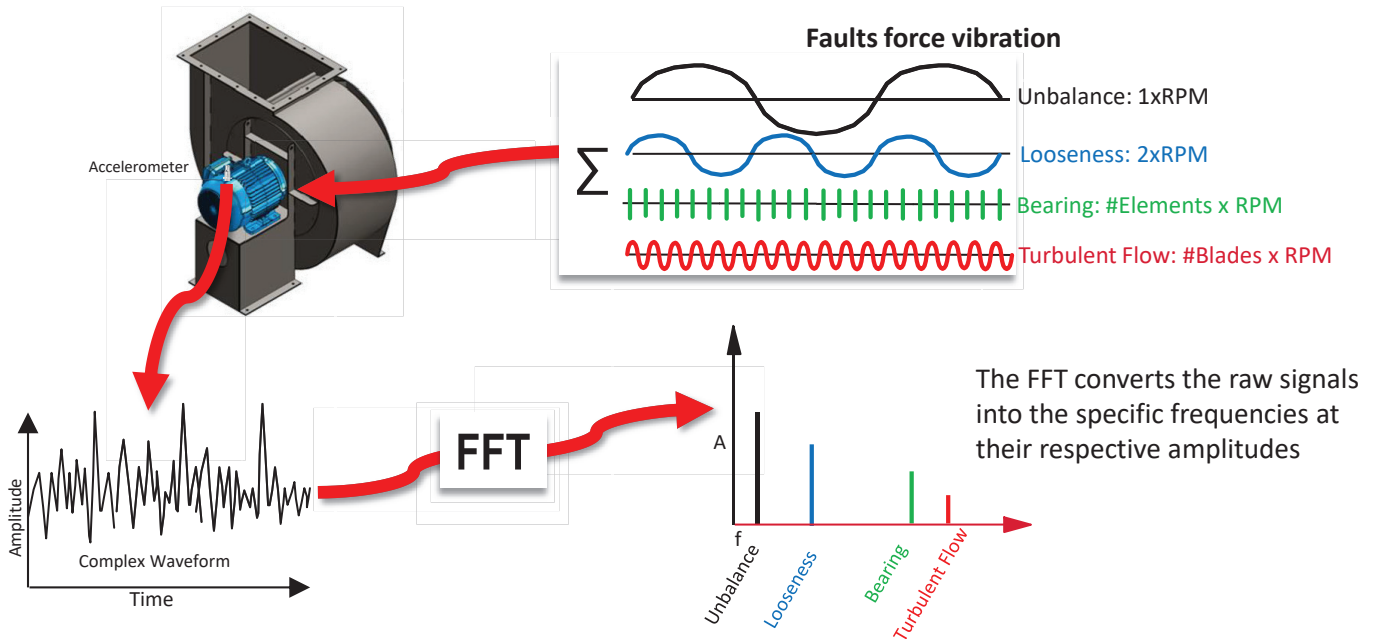


Imbalanced rotors, misaligned shafts...

# Monitoring Machine Condition...

The FFT separates the individual *frequencies* from the raw signal

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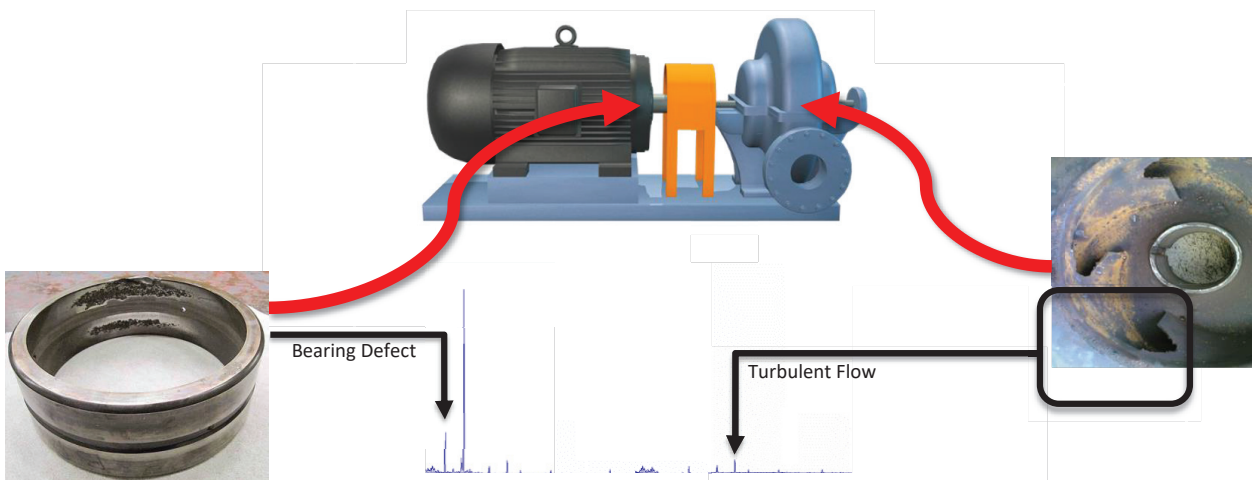
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# Monitoring Machine Condition...

A simple example

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- Vibrations at these frequencies indicate the presence of a specific condition or fault\*
- The magnitude of the vibration is an indication of the severity of the condition or fault

\*or, sometimes, one of several faults that could cause vibration at the same frequency.

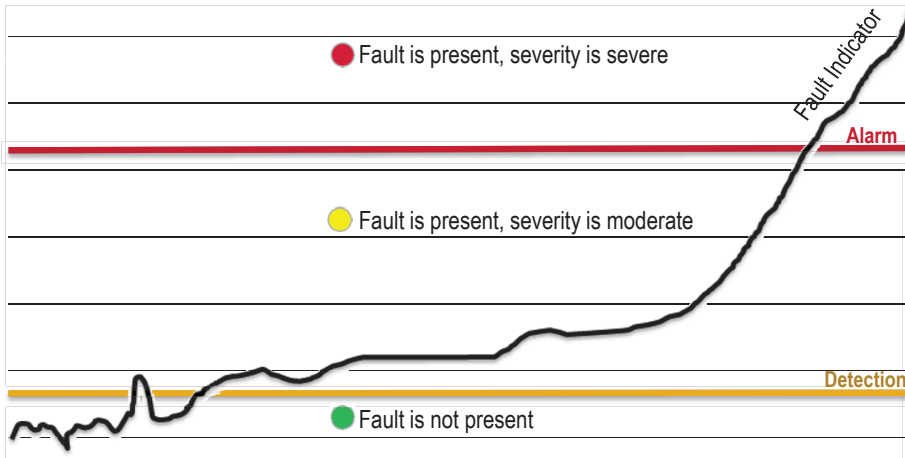
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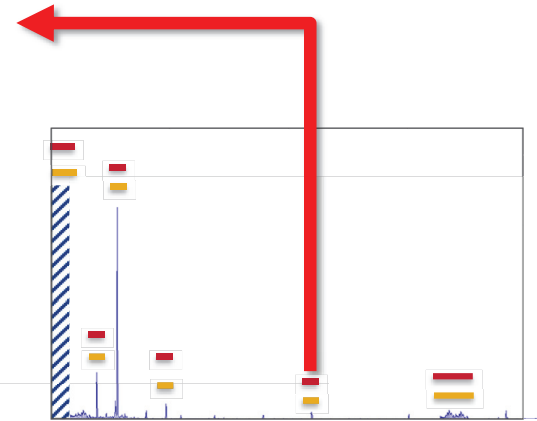
# Monitoring Machine Condition...

By trending fault indicators

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Continued operation above "Alarm" may result in damage to components other than the wearable component, which will cause longer and more expensive repairs.

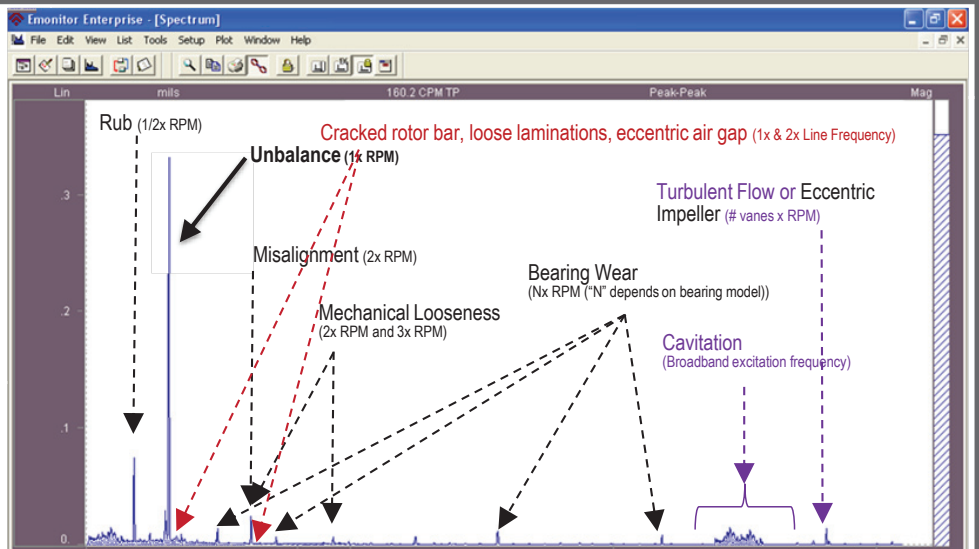
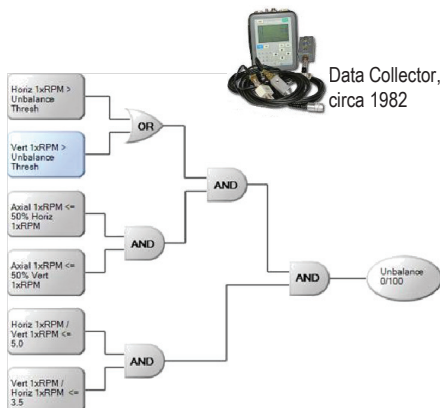


# Monitoring Machine Condition...

Proven Technology

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- We have been analyzing machine vibration for over 30 years. We *know* what it means!



Mechanical & electrical faults and many process conditions force vibration at specific, predictable, frequencies



# Fault Indicators in Logix

## Integrated Fault Detection and Identification

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- Tags represent the **tools** used to measure the considered **fault indicators**

- Alarms signal detection
- Trends monitor propagation

- This is what Dynamix does!

Dynamix provides the measurement, signal processing and integration tools necessary to present the indicators of condition or fault, configurable for any machine, to Logix as simple tags over EtherNet/IP.

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# Fault Indicators in the IA

## Integrated Visualization

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- True machine condition made “part of what you do”.
  - Fault Indicators can be acted on, the same as any other tags.
  - Fault Indicators can be presented on faceplates and other HMI’s the same as any other tags.
  - Fault Indicators can be written to an historian and trended the same as any other tags.

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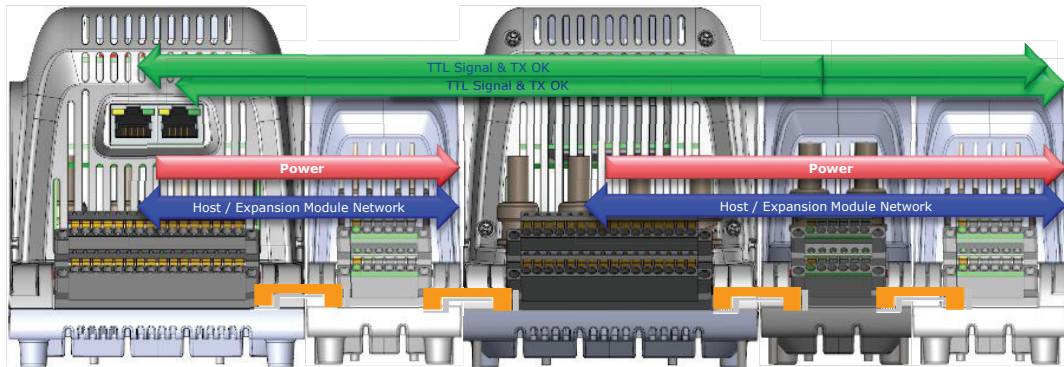
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# Dynamix 1444 Series

## Architecture & Local Bus

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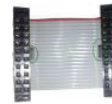


### Architecture

- Network Connections on Main Module
- Insert / Remove Under Power
- Interconnect via included ribbon cable between terminal bases

### Local Bus

- Host / Expansion Module Communications
- Speed Signal Distribution
- Power Distribution



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# Functional Summary

## Capabilities

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### ■ The capabilities necessary to serve any application

#### ■ Machinery Protection

- General machine protection
- API-670 compliant protection

#### ■ Machine Condition Monitoring

- Production assurance (uptime)
- Condition based maintenance
- Quality

#### ■ Vibration

- Acceleration
- Velocity
- Displacement
- Absolute Shaft Vibration
- Spike Energy (gSE)

#### ■ Speed

#### ■ Pressure

#### ■ Thrust

#### ■ Case Expansion

#### ■ Differential Expansion

#### ■ Rod Drop

#### ■ Relays

#### ■ 4-20mA Outputs

#### ■ Event Capture

#### ■ Event Log

#### ■ Trend / Alarm

#### ■ Startup /

#### Coastdown

Real Time, Continuous, Surveillance

Real Time Processing of Critical Parameters,  
Continuous Processing of Diagnostic Data, Demand  
Processing of Infrequent Measures



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# Functional Summary

## Measurements

### ■ The measurements necessary to monitor any kind of machine

- Dynamic (AC) Measurements
  - Discrete Measurements
    - Per Channel Pair
      - SMAX Magnitude
      - Shaft Absolute Vibration
    - Per Channel
      - Overall (2)
      - Order Magnitude & Phase (4)
      - FFT Band (8)
      - Not 1x (1)
      - Bias / Gap (1)
      - gSE Overall (1)
  - Complex Measurements
    - TWF and FFT (to 1800 lines)
    - Asynchronous and Synchronous
- Static (DC) Measurements
  - Single DC Channels
    - Axial Position
      - Thrust
      - Valve Position
    - Eccentricity
    - Rod Drop
    - Proportional Voltage
  - Paired DC Channels
    - Differential Expansion
- Demand Measurements
  - Synchronous, Asynchronous TWF and FFT (to 14,400 lines)
  - Simultaneous Cross Module Measurements
- Speed Measurements
  - Speed
    - Retains maximum speed measured
  - Rate of change of speed

# Functional Summary

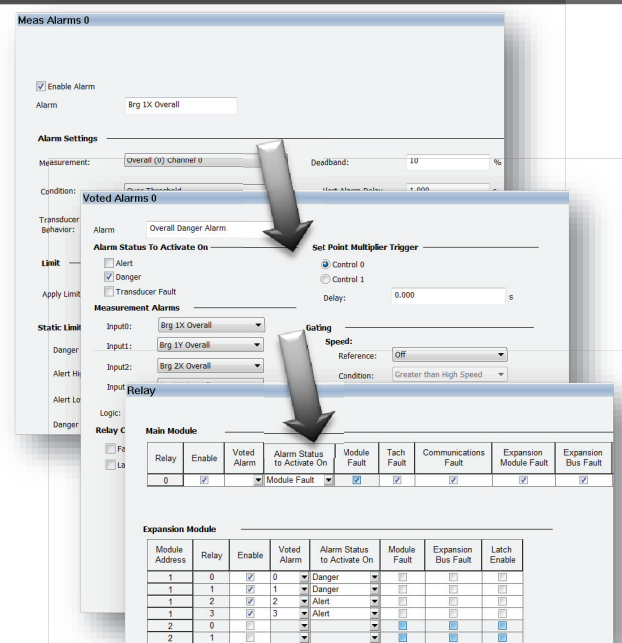
## Alarms and Relays

### ■ Alarm and relay solutions necessary to meet any requirement

- Measurement Alarms
  - Apply limits to measured parameter
  - 24 measurement alarms may be defined
- Voted Alarms
  - Apply voting logic to Measurement Alarms
  - 13 voted alarms may be defined
- Relays

Main modules include a single onboard physical relay. With expansion modules this can be expanded to 5, 9 or 13 relays

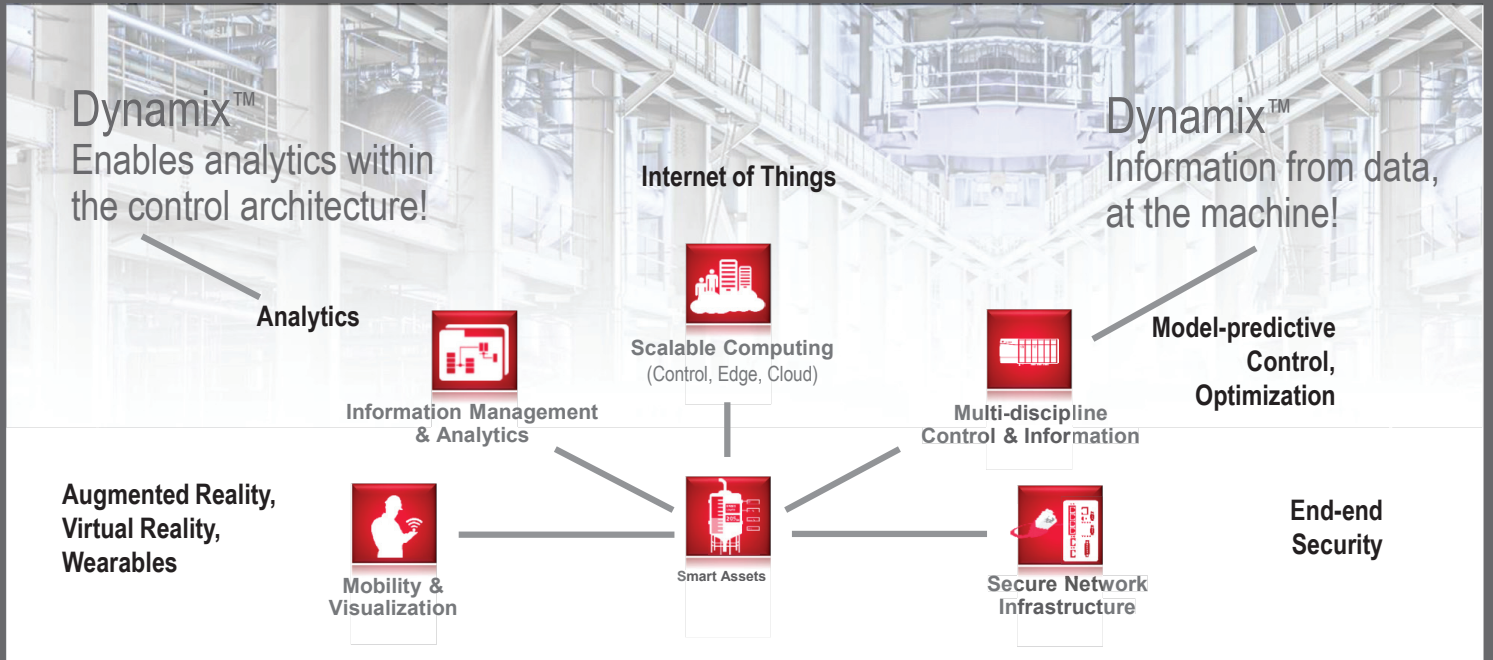
- Associate with any voted alarm, or...
- Leave unassigned to actuate only on fault.



# Dynamix in the Integrated Architecture

Part of the Connected Enterprise

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# Dynamix in the Integrated Architecture

Controller I/O

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Supported by Logix

I/O is provided and managed the same way as for any device.

- Requires Logix version
  - V24+
  - V24.51+ Redundancy
- Configuration
  - Provided by an Add On Profile
- Assemblies
  - Configuration
  - Input
    - User selectable tags for input
  - Output
    - User selectable tags for output



**Controller Output**

Control Bits	Data
Trip Inhibit	Speeds (2)
Set Point Multiply (2)	Alarm Limits (16)
Gate Controls (2)	
Alarm Reset	
Alarm Buffer Trigger	
Alarm Buffer Reset	
Transient Buffer Resets (4)	

**Controller Input**  
Input Assembly parameters selected in Module Definition.

Select Channel Data to be added to the Input Tag

<input checked="" type="checkbox"/> Speed (0)	<input type="checkbox"/> Speed (1)
<input type="checkbox"/> Factored Speed (0)	<input type="checkbox"/> Factored Speed (1)
<input type="checkbox"/> Speed (0) Maximum	<input type="checkbox"/> Speed (1) Maximum
<input type="checkbox"/> Speed (0) Rate of Change	<input type="checkbox"/> Speed (1) Rate of Change

Channel Pairs

0, 1    2, 3    Copy

<input type="checkbox"/> SMax Pk-Pk	<input type="checkbox"/> Axial Differential Expansion
<input type="checkbox"/> Shaft Absolute Pk-Pk	<input type="checkbox"/> Radial Differential Expansion

Channel

<input type="checkbox"/> Overall (0)	<input checked="" type="checkbox"/> FFT Band (0)
<input checked="" type="checkbox"/> Overall (1)	<input checked="" type="checkbox"/> FFT Band (1)
<input checked="" type="checkbox"/> Order (0) Magnitude	<input type="checkbox"/> FFT Band (2)
<input checked="" type="checkbox"/> Order (0) Phase	<input type="checkbox"/> FFT Band (3)
<input type="checkbox"/> Order (1) Magnitude	<input type="checkbox"/> FFT Band (4)
<input type="checkbox"/> Order (1) Phase	<input type="checkbox"/> FFT Band (5)
<input type="checkbox"/> Order (2) Magnitude	<input type="checkbox"/> FFT Band (6)
<input type="checkbox"/> Order (2) Phase	<input type="checkbox"/> FFT Band (7)
<input type="checkbox"/> Order (3) Magnitude	<input type="checkbox"/> Not 1x
<input type="checkbox"/> Order (3) Phase	<input type="checkbox"/> Proportional DC
<input checked="" type="checkbox"/> Bias / Gap	<input type="checkbox"/> Rod Drop

Controller Organizer

- Controller Demo
  - Controller Tags
  - Controller Fault Handler
  - Power-Up Handler
- Tasks
  - MainTask
  - MainProgram
  - Unscheduled
- Motion Groups
  - Ungrouped Axes
  - Add-On Instructions
  - Data Types
    - User-Defined
    - Add-On-Defined
    - Predefined
    - Module-Defined
  - Trends
  - Logical Model
  - I/O Configuration
    - PointIO
      - [0] 1769-L18ERM-BB1B Demo
      - Embedded I/O
        - [1] Embedded Discrete\_IO
      - Expansion I/O, 0 Modules
    - Ethernet
      - 1769-L18ERM-BB1B Demo
      - 1444-DYN04-01RA/A Demo
- Module Defined Tags
  - Demo1
  - Demo-O
  - Demo-C

Description	Status
Module Fault	Running

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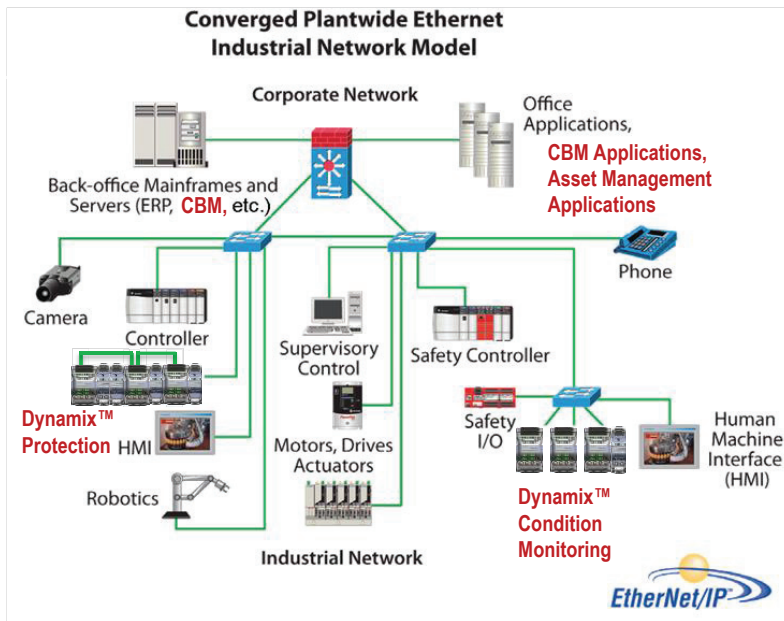
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# Our EtherNet/IP Network Strategy

## With Dynamix

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From the beginning the **Dynamix 1444 Series** was **designed** and **developed** to execute this core Rockwell Automation strategy.

Native dual port **Ethernet**, the **EtherNet/IP** protocol, **Device Level Ring**, an integrated **Logix** solution, and all of the products and capabilities of Rockwell Automation's **Integrated Architecture**...

These are what makes the **Dynamix 1444 Series** the industries most **open yet secure, integrated** and **capable** solution for **machinery monitoring and protection** available today.

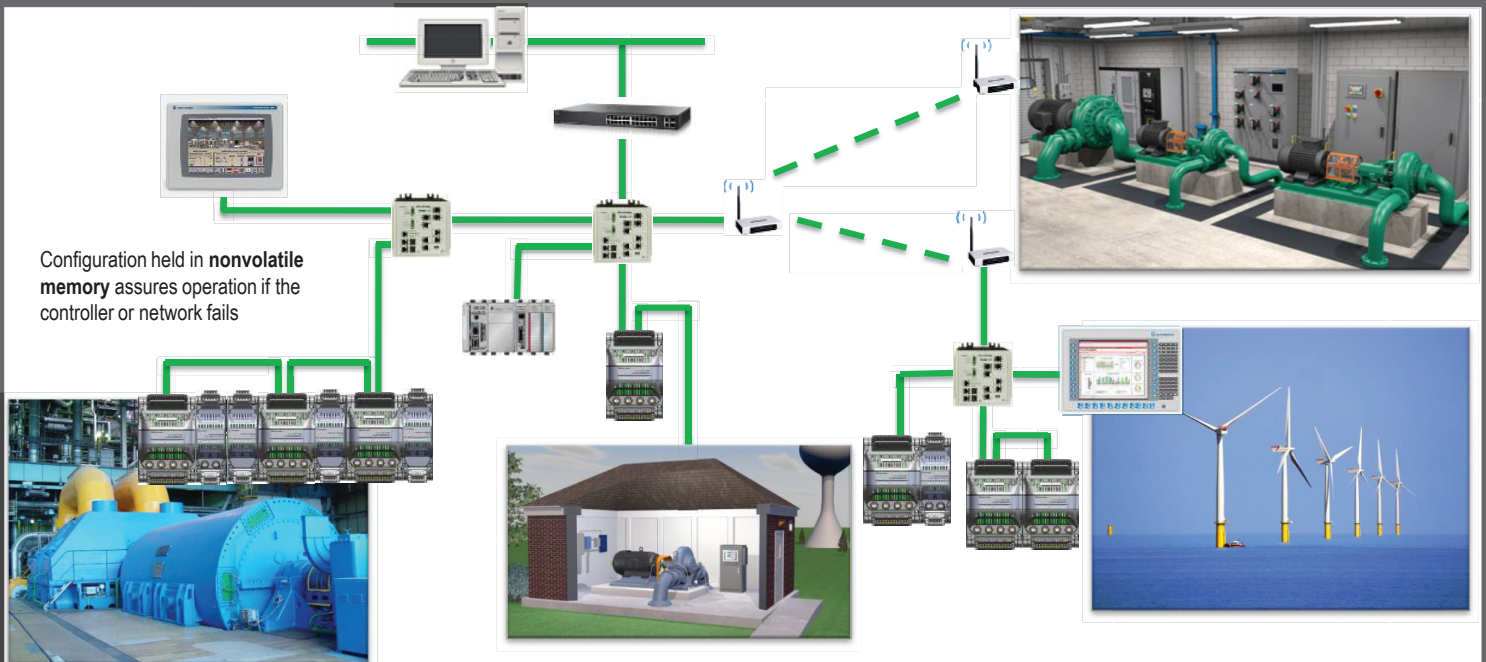
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# Dynamix System Architectures

## Dedicated Condition Monitoring System

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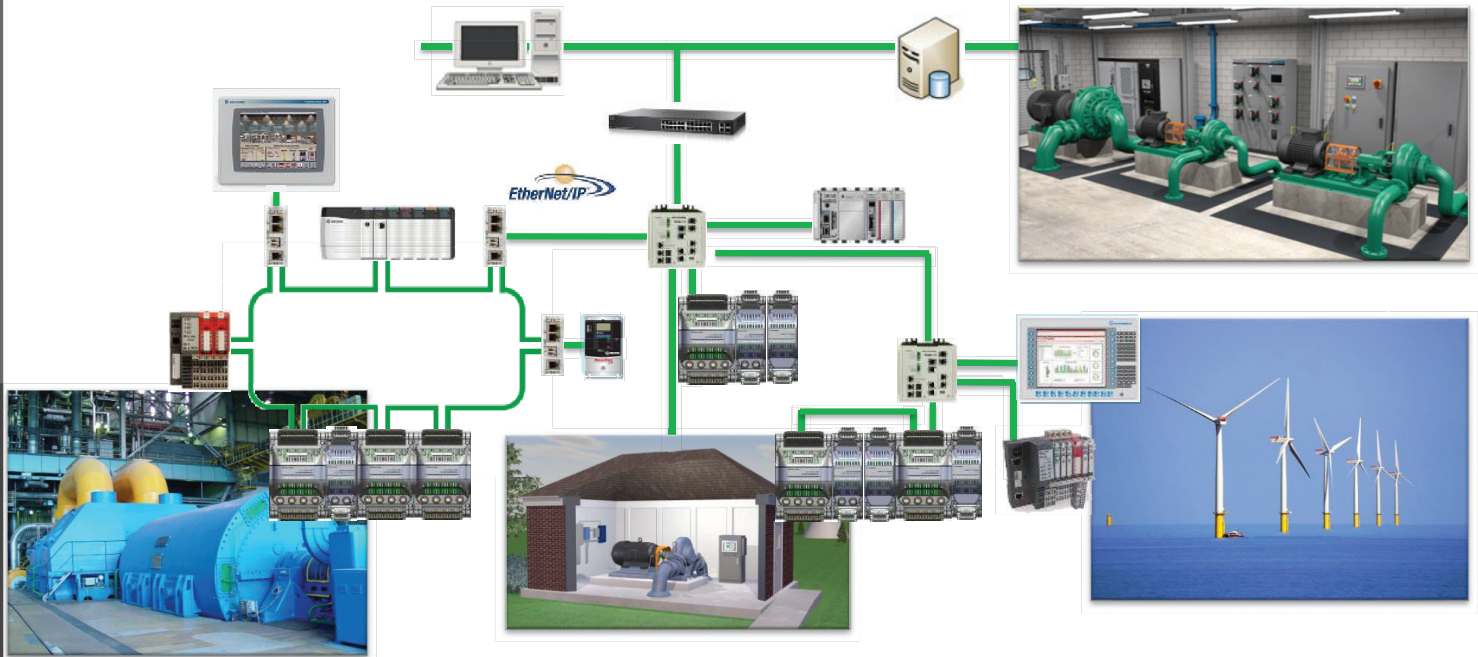
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# Dynamix System Architectures

Condition Monitoring within an Integrated Architecture

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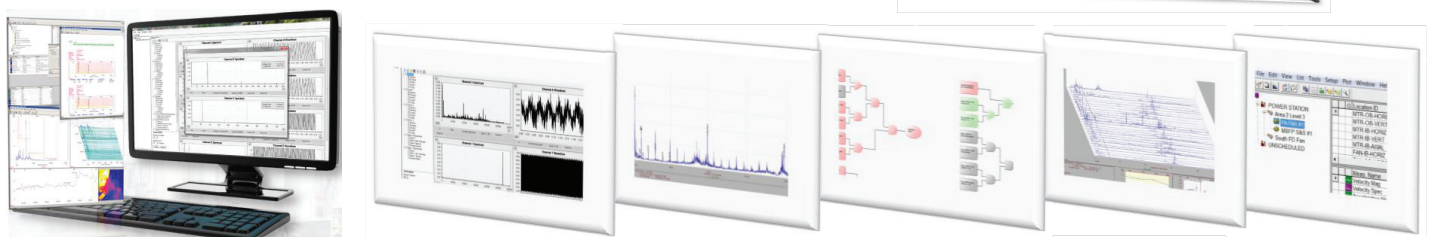
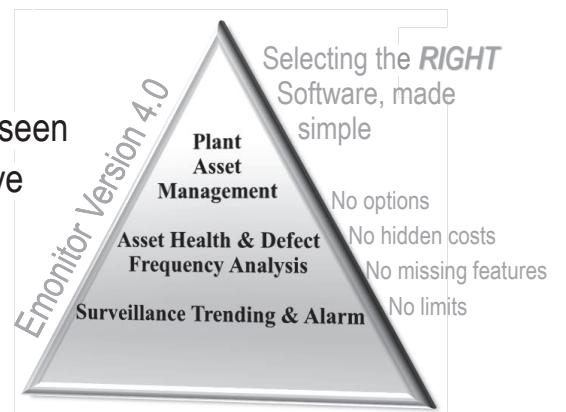
# Emonitor CMS

Condition Monitoring Software for Dynamix

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- Because sometimes...
  - The problem is "Other"
  - The actual time waveforms and spectrum must be seen
  - Dynamix 1444 monitor is a part of a larger predictive maintenance program

When "Other" happens, when the solution requires **data** and the **tools** required by **Condition Monitoring Professionals**, there's Emonitor CMS.



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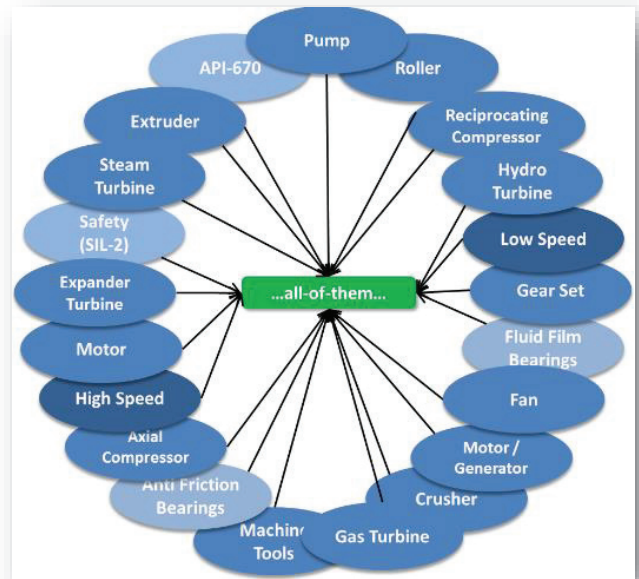
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# The Dynamix 1444 Series

And the Integrated Architecture

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- An architecture with a single core module that:
  - Can be applied to any Machinery Protection application
  - Can serve any Condition Monitoring Application
  - Applies a native EtherNet/IP backplane
  - Is a component of Rockwell Automation's Integrated Architecture



# Integrated Condition Monitoring

from Rockwell Automation

**Rockwell Automation**

## Dynamix™ 1444 Monitors:

- Integrated condition monitoring
- API-670 capable machinery protection
- Smart machine monitoring...
  - Automated fault detection and identification within the Integrated Architecture
- Secure configuration in Logix Designer



## Dynamix™ 2500 Portables:

- Data collector for predictive maintenance and machinery vibration diagnostics.
  - Part of a comprehensive CbM program
  - Download your measurements to Emonitor CMS
- A real-time, multi-channel signal analyzer
  - A stand alone instrument for use in balancing, run up / coastdown analysis, bump testing and more.



## Emonitor CMS Software:

- Proven, comprehensive tools for executing any size condition based monitoring program
- Online and offline analysis and data collection
- Automated diagnostics
  - Fault frequency identification
  - Built-in and user editable rule sets



## Sensors:

- 1442 Series Eddy Current Probes
  - API-670 compliant sensors, extension cables and drivers for all common size and range requirements
- 1443 Series Sensors
  - Industrial accelerometers, cables and mounting solutions

